

Name: \_\_\_\_\_ Period: \_\_\_\_\_ Date: \_\_\_\_\_

# What is a Robot?

There are many different kinds of robots, from ones designed to build cars to ones that vacuum to ones that explore other planets. To be a robot, a machine must meet certain criteria. A machine is only a robot if it has all the elements listed below:

## Body

The body is a physical substance and shape of some type. The body will be designed based on the function—some look like vehicles, some like an arm, and some like a person. If you can touch it, that's the body.

## Control

Control is a program to control the robot. Robots must be told what to do. To control a robot we need:

### Input

Input is the information that comes from the robot's sensors. Robots have sensors that they use to get information from the robot's environment. For example, a smoke detector can detect smoke. (In other words, sensing the robot's environment). Robots typically have external and internal sensors.

### Programmable

The program is a set of instructions or rules that the programmer gives the robot. For example, a smoke detector has a program to make a sound if it senses smoke. To be a robot, a machine must be programmable.

### Output

The output is the actions a robot takes, often involving motors, lights, or sounds. For example, a smoke detector makes a loud sound and might flash lights. (In other words, effecting change in the robot's environment—adapting.)

## Behavior

Behavior is the combination of outputs that result in the task or job the robot does. For example, the behavior of a smoke detector is to "go off" in the presence of smoke. "Going off" is a combination of making noise and flashing lights, and may also involve calling the fire department.

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# Are We Robots?

## Directions:

Below is a list of machines that you might encounter in your daily life. Add machines to the bottom. Complete the table by deciding if the machine meets the criteria for being a robot. Then determine if the machine is a robot.

Body—physical form of some kind

Control—

Input—gets information from sensors, buttons, etc.

Program—is programmable, follows a set of instructions you give it

Output—an action it takes

Behavior—wht it does; the function it performs

	<b>BODY</b>	<b>INPUT</b>	<b>PROGRAM</b>	<b>OUTPUT</b>	<b>BEHAVIOR</b>	<b>IS IT A ROBOT?</b>
Stove						
Microwave						
Radio						
iPod						
Flashlight						
Bicycle						
Car						
Alarm clock						
Traffic light						
Photocopier						
Computer						
Mars Rover						
Sewing Machine						
Smart phone						